

# Mathematics 222B Lecture 15 Notes

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## 1 Unique Continuation for Elliptic PDEs and Introduction to Hyperbolic PDEs

### 1.1 Unique continuation for elliptic PDEs

The original plan was for this lecture to cover one final topic for elliptic PDEs: unique continuation. Here is the main theorem.

**Theorem 1.1** (Aronszajn). *Let  $U \subseteq \mathbb{R}^d$  be open and connected, and consider the elliptic partial differential operator  $P$  with*

$$Pu = -\partial_j(a^{j,k}\partial_k u) + b^j\partial_j u + cu,$$

*where  $a^{j,k}, b^j, c \in C^\infty(U)$  with  $a \succ \lambda I$  in  $U$ . Let  $u \in H^1(U)$ . If  $Pu = 0$  in  $U$  and  $u = 0$  in a nonempty open subset  $Q \subseteq U$ , then  $u = 0$  in  $U$ .*

For holomorphic functions, the way we prove this is to say that holomorphic functions are analytic and look at the domain of convergence of a Taylor series. The way we prove this for solutions to elliptic PDEs is via an a priori estimate.

**Lemma 1.1** (Carleman estimate). *Let  $v \in C_c^\infty(\mathbb{R}^d)$ . and suppose that  $\nabla\psi \neq 0$ . Then*

$$t^2\|e^{t\psi}v\|_{L^2} + t\|e^{t\psi}\nabla v\|_{L^2} \leq C\|e^{t\psi}Pv\|_{L^2}.$$

A good reference for this is the book *Carleman Estimates* by Lerner. This is related to inverse problems and other non-well-posed problems in PDEs.

### 1.2 Linear hyperbolic PDEs

Instead of formally defining what a hyperbolic PDE is, which is difficult and not entirely productive. Instead, we will give a ‘working definition’ of how people think of hyperbolic PDEs.

**Definition 1.1.** A **hyperbolic PDE** is an evolutionary PDE with two characteristics:

- “#/order of time derivatives” = “#/order of space derivatives”.
- (local) well-posedness of the initial value problem

$$\begin{cases} P\phi = 0 \\ (\phi, \partial_t \phi, \dots, \partial_t^{N-1} \phi)|_{t=0} = (g_0, \dots, g_{N-1}), \end{cases}$$

where  $N$  is the order of the time derivatives.

This second condition is really what people think of when they talk about hyperbolic PDEs.

**Example 1.1.** The wave equation  $(-\partial_t^2 + \Delta)\phi = 0$  is hyperbolic.

**Example 1.2.** The equation  $(-\partial_t + x^j \partial_j)\phi = 0$  is hyperbolic.

**Example 1.3** (Non-examples). The heat equation  $(\partial_t - \Delta)\phi = 0$  and the Schrödinger equation  $(\partial_t - i\Delta)\phi = 0$  are *dispersive* but not hyperbolic.

**Example 1.4.** The Laplace equation  $(\partial_t^2 + \Delta)\phi = 0$  is not hyperbolic because it does not have local well-posedness of the initial value problem.

Local well-posedness of the initial value problem is related to the energy estimate.

**Example 1.5** (Linear constant coefficient system). Let

$$\Phi = \begin{bmatrix} \Phi^{(1)} \\ \vdots \\ \Phi^{(n)} \end{bmatrix},$$

and suppose we have a system of linear, constant coefficient PDEs

$$B\partial_t \Phi = A^j \partial_{x^j} \Phi,$$

where  $A$  is an  $n \times n$  matrix. Without loss of generality, assume we have

$$\partial_t \Phi = A^j \partial_{x^j} \Phi,$$

What guarantees uniqueness of a solution to the initial value problem? That is, what condition do we need on  $A$  to guarantee the validity of the energy estimate?

$$\int_{\mathbb{R}^d} \underbrace{\Phi^{(k)} \partial_t \Phi^{(k)}}_{=\frac{1}{2} \partial_t \int \Phi^{(k)} \Phi^{(k)}} + \underbrace{\Phi^{(k)} (A^j)_{(\ell)}^{(k)} \partial_j \Phi^{(\ell)}}_{\frac{1}{2} \int (A^j)_{(\ell)}^{(k)} \Phi^{(k)} \partial_j \Phi^{(\ell)} - \frac{1}{2} (A^j)_{(\ell)}^{(k)} \partial_j \Phi^{(k)} \Phi^{(\ell)}} dx = \int \Phi^{(k)} F^{(k)} dx.$$

We get the following identity:

$$\frac{1}{2}\partial_t \int |\Phi|^2 dx + \frac{1}{2} \int ((A^j)^{(k)}_{(\ell)} - (A^j)^{(\ell)}_{(k)}) \Phi^{(k)} \partial_j \Phi^{(\ell)} dx = \int F \cdot \Phi dx,$$

where the second term is 0 if  $A^j$  is symmetric.

This tells us that if  $A^j$  is symmetric, then the energy estimate holds:

$$\int |\Phi|^2(t) dx = \int |\Phi|^2(0) dx + \int_0^t \int F \cdot \Phi dx dt.$$

This gives uniqueness

**Theorem 1.2.** *The linear, constant coefficient system*

$$\partial_t \Phi = A^j \partial_{x_j} \Phi$$

*is hyperbolic if and only if the  $A^j$  are symmetric. That is the initial value problem is well-posed in  $L^2$ , meaning for every  $\Phi_0 \in L^2(\mathbb{R}^d)$ , and  $F \in L^1_t((-\infty, \infty); L^2_x)$ , there exists a unique  $\Phi \in C_t((-\infty, \infty); L^2_x)$  solving the system.*

We use the notation  $\phi \in C_t(I; X)$  to mean that the function  $\phi : I \rightarrow X$  sending  $t \mapsto \phi(t)$  is continuous, where  $C_t(I; X)$  has the norm

$$\|\phi\|_{C_t(I; X)} := \sup_{t \in I} \|\phi(t, \cdot)\|_X = \|\phi\|_{L_t^\infty(X)} < \infty.$$

**Example 1.6** (1st order formulation of  $\square\phi = f$ ). Let the **d'Alembertian** be  $\square = -\partial_t^2 + \Delta$ . Then

$$\square\phi = f \iff \partial_t\phi = \psi, \partial_t\psi = \Delta\phi - f.$$

We can write this system as

$$\partial_t \begin{bmatrix} \phi \\ \psi \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ \Delta & 0 \end{bmatrix} \begin{bmatrix} \phi \\ \psi \end{bmatrix} - \begin{bmatrix} 0 \\ f \end{bmatrix}.$$

If we take the Fourier transform of the matrix, we get

$$\begin{bmatrix} 0 & 1 \\ -|\xi|^2 & 0 \end{bmatrix}.$$

and if we diagonalize this, we get

$$\begin{bmatrix} +i|\xi| & 0 \\ 0 & -i|\xi| \end{bmatrix},$$

which is anti-Hermitian. This means that the energy estimate will hold in the diagonalized variables

### 1.3 Goals for studying hyperbolic PDEs

Here are our goals for studying hyperbolic PDEs:

1. (Local) well-posedness of the initial value problem for variable-coefficient wave equations,

$$P\phi = \partial_\mu(g^{\mu,\nu}\partial_\nu\phi) + b^\mu\partial_\mu\phi + c\phi,$$

where  $g$  is a **Lorentzian metric**, a non-degenerate symmetric  $(d+1) \times (d+1)$  matrix with signature  $(-, +, +, \dots, +)$  (meaning that the eigenvalues of  $g$  have signs  $-, +, +, \dots, +$ ). This condition can also be stated as: for every  $(t, x)$ , there exists an invertible matrix  $M$  such that  $M^{-1}g(t, x)M = \text{diag}(-1, +1, +1, \dots, +1)$ .

**Example 1.7.** When  $g = \text{diag}(-1, +1, +1, \dots, +1)$  and  $b = c = 0$ ,  $P = \square$ .

2. Long-time behavior of the solutions: If we look at this in general, it immediately becomes a research topic.<sup>1</sup> Instead, we will focus on long-time behavior of solutions to equations where  $P$  is a small variant of  $\square$ .

### 1.4 Grönwall's inequality

Our treatment for the well-posedness of the initial value problem for variable coefficient wave equations will be closer to Ringström's book *the Cauchy Problem in General Relativity* than it will be to Evans' book.

Our setting is

$$P\phi = \partial_\mu(g^{\mu,\nu}\partial_\nu\phi) + b^\mu\partial_\mu\phi + c\phi.$$

We want to derive energy estimates for

$$\begin{cases} P\phi = f & \text{in } \mathbb{R}_+ \times \mathbb{R}^d, \\ (\phi, \partial_t\phi)|_{t=0} = (g, h) & \text{on } \{t=0\} \times \mathbb{R}^d. \end{cases}$$

We need the following preliminary tool, which was discussed in Math 222A.

**Lemma 1.2** (Grönwall's inequality). *Suppose that  $E(t) \in C_t([0, T])$  and  $r(t) \in L_t^1([0, T])$  with  $E, r \geq 0$  satisfy the inequality*

$$E(t) \leq E_0 + \int_0^t r(t')E(t') dt' \quad \forall 0 \leq t \leq T.$$

*Then*

$$E(t) \leq E_0 \exp\left(\int_0^t r(t') dt'\right) \quad \forall 0 \leq t \leq T.$$

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<sup>1</sup>Scattering theory is devoted to studying these problems.

We give a proof that uses a **bootstrap argument**, i.e. continuous induction on time. First, here is a motivating computation: Take the inequality we are given, and plug in the answer into the right hand side. We get

$$E(t) \leq E_0 + E_0 \int_0^t r(t') \exp \left( \underbrace{\int_0^{t'} r(t'') dt''}_{R(t')} \right) dt,$$

where  $R$  is just an antiderivative of  $r$ .

$$\begin{aligned} &= E_0 + E_0 \left( \exp \left( \int_0^t r(t') dt' \right) - 1 \right) \\ &= E_0 \exp \left( \int_0^t r(t') dt' \right). \end{aligned}$$

This tells us that the solution is what we get if we try to find a fixed point when iterating the use of this bound.

*Proof.* Note that it suffices to prove the inequality

$$E(t) \leq E_0(1 + \delta) \exp \left( \int_0^t r(t') dt' \right)$$

on  $[0, T]$  for all  $\delta$ . Also note that for some  $T_0$ , this inequality holds on  $[0, T_0]$  by continuity.

Now assume that

$$E(t) \leq E_0(1 + \delta) \exp \left( \int_0^t r(t') dt' \right)$$

on  $[0, T]$ . If we plug this bound into the iteration, we get

$$\begin{aligned} E(t) &\leq E_0 + E_0(1 + \delta) \int_0^t r(t') \exp \left( \int_0^{t'} r(t'') dt'' \right) dt' \\ &= E_0 + E_0(1 + \delta) \left( \exp \left( \int_0^t r(t') dt' \right) - 1 \right) \\ &= E_0(1 + \delta) \exp \left( \int_0^t r(t') dt' \right) - \underbrace{\delta E_0}_{>0}. \end{aligned}$$

This means that this bound we assumed holds on  $[0, T' + \varepsilon]$  for some  $\varepsilon$ . The result now holds by trying to do this with the supremum of all  $T'$  such that this inequality holds on  $[0, T']$ . We get that this supremum must be  $T$ .  $\square$